## SIEMENS

## Data sheet

## 3RW5543-6HA14



SIRIUS soft starter 200-480 V 210 A, 110-250 V AC Screw terminals

product brand name	SIRIUS				
product category	Hybrid switching devices				
product designation	Soft starter				
product type designation	3RW55				
manufacturer's article number					
<ul> <li>of high feature HMI module usable</li> </ul>	<u>3RW5980-0HF00</u>				
<ul> <li>of communication module PROFINET standard usable</li> </ul>	<u>3RW5980-0CS00</u>				
<ul> <li>of communication module PROFINET high-feature usable</li> </ul>	<u>3RW5950-0CH00</u>				
<ul> <li>of communication module PROFIBUS usable</li> </ul>	<u>3RW5980-0CP00</u>				
<ul> <li>of communication module Modbus TCP usable</li> </ul>	<u>3RW5980-0CT00</u>				
<ul> <li>of communication module Modbus RTU usable</li> </ul>	<u>3RW5980-0CR00</u>				
<ul> <li>of communication module Ethernet/IP</li> </ul>	<u>3RW5980-0CE00</u>				
<ul> <li>of circuit breaker usable at 400 V</li> </ul>	3VA2325-7MN32-0AA0; Type of coordination 1, Iq = 65 kA, CLASS 10				
<ul> <li>of circuit breaker usable at 500 V</li> </ul>	3VA2325-7MN32-0AA0; Type of coordination 1, Iq = 65 kA, CLASS 10				
<ul> <li>of circuit breaker usable at 400 V at inside-delta circuit</li> </ul>	3VA2440-7MN32-0AA0; Type of coordination 1, Iq = 65 kA, CLASS 10				
<ul> <li>of circuit breaker usable at 500 V at inside-delta circuit</li> </ul>	3VA2440-7MN32-0AA0; Type of coordination 1, Iq = 65 kA, CLASS 10				
<ul> <li>of the gG fuse usable up to 690 V</li> </ul>	2x3NA3354-6; Type of coordination 1, Iq = 65 kA				
<ul> <li>of the gG fuse usable at inside-delta circuit up to 500 V</li> </ul>	2x3NA3354-6; Type of coordination 1, Iq = 65 kA				
<ul> <li>of full range R fuse link for semiconductor protection usable up to 690 V</li> </ul>	<u>3NE1230-2; for supply systems up to 500 V; type of coordination 2, Iq = 65 kA</u>				
<ul> <li>of back-up R fuse link for semiconductor protection usable up to 690 V</li> </ul>	<u>3NE3333; Type of coordination 2, Iq = 65 kA</u>				
General technical data					
starting voltage [%]	20 100 %				
stopping voltage [%]	50 %; non-adjustable				
start-up ramp time of soft starter	0 360 5				

0 011			
stopping voltage [%]	50 %; non-adjustable		
start-up ramp time of soft starter	0 360 s		
ramp-down time of soft starter	0 360 s		
start torque [%]	10 100 %		
stopping torque [%]	10 100 %		
torque limitation [%]	20 200 %		
current limiting value [%] adjustable	125 800 %		
breakaway voltage [%] adjustable	40 100 %		
breakaway time adjustable	0 2 s		
number of parameter sets	3		
accuracy class	5 (based on IEC 61557-12)		
certificate of suitability			
CE marking	Yes		
UL approval	Yes		

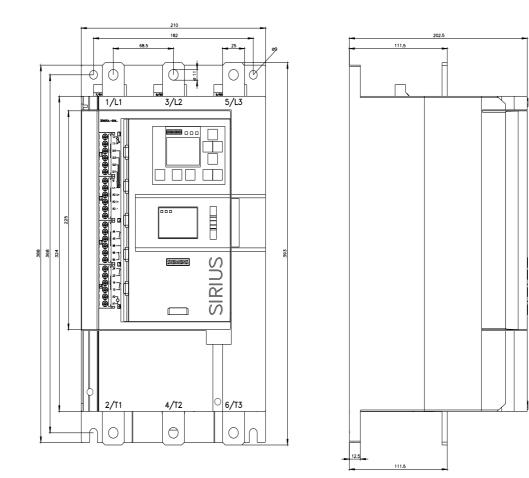
CSA approval	Yes
product component	
HMI-High Feature	Yes
<ul> <li>is supported HMI-High Feature</li> </ul>	Yes
product feature integrated bypass contact system	Yes
number of controlled phases	3
current unbalance limiting value [%]	10 60 %
ground-fault monitoring limiting value [%]	10 95 %
buffering time in the event of power failure	
<ul> <li>for main current circuit</li> </ul>	100 ms
for control circuit	100 ms
idle time adjustable	0 255 s
insulation voltage rated value	480 V
degree of pollution	3, acc. to IEC 60947-4-2
impulse voltage rated value	6 kV
blocking voltage of the thyristor maximum	1 400 V
service factor	1.15
surge voltage resistance rated value	6 kV
maximum permissible voltage for protective separation	
<ul> <li>between main and auxiliary circuit</li> </ul>	480 V; does not apply for thermistor connection
shock resistance	15 g / 11 ms, from 6 g / 11 ms with potential contact lifting
recovery time after overload trip adjustable	60 1 800 s
utilization category according to IEC 60947-4-2	AC 53a
reference code according to IEC 81346-2	Q
Substance Prohibitance (Date)	02/15/2018
SVHC substance name	Lead - 7439-92-1 Lead monoxide (lead oxide) - 1317-36-8 2-methyl-1-(4-methylthiophenyl)-2-morpholinopropan-1-one - 71868-10-5 Dibutylbis(pentane-2,4-dionato-O,O')tin - 22673-19-4 Dicyclohexyl phthalate (DCHP) - 84-61-7 Dodecamethylcyclohexasiloxane (D6) - 540-97-6 Lead titanium trioxide - 12060-00-3
product function	
<ul> <li>ramp-up (soft starting)</li> </ul>	Yes
• ramp-down (soft stop)	Yes
<ul><li>ramp-down (soft stop)</li><li>breakaway pulse</li></ul>	Yes Yes
<ul> <li>ramp-down (soft stop)</li> <li>breakaway pulse</li> <li>adjustable current limitation</li> </ul>	Yes Yes Yes
<ul> <li>ramp-down (soft stop)</li> <li>breakaway pulse</li> <li>adjustable current limitation</li> <li>creep speed in both directions of rotation</li> </ul>	Yes Yes Yes
<ul> <li>ramp-down (soft stop)</li> <li>breakaway pulse</li> <li>adjustable current limitation</li> <li>creep speed in both directions of rotation</li> <li>pump ramp down</li> </ul>	Yes Yes Yes Yes
<ul> <li>ramp-down (soft stop)</li> <li>breakaway pulse</li> <li>adjustable current limitation</li> <li>creep speed in both directions of rotation</li> <li>pump ramp down</li> <li>DC braking</li> </ul>	Yes Yes Yes Yes Yes
<ul> <li>ramp-down (soft stop)</li> <li>breakaway pulse</li> <li>adjustable current limitation</li> <li>creep speed in both directions of rotation</li> <li>pump ramp down</li> <li>DC braking</li> <li>motor heating</li> </ul>	Yes Yes Yes Yes Yes Yes
<ul> <li>ramp-down (soft stop)</li> <li>breakaway pulse</li> <li>adjustable current limitation</li> <li>creep speed in both directions of rotation</li> <li>pump ramp down</li> <li>DC braking</li> <li>motor heating</li> <li>slave pointer function</li> </ul>	Yes Yes Yes Yes Yes Yes Yes
<ul> <li>ramp-down (soft stop)</li> <li>breakaway pulse</li> <li>adjustable current limitation</li> <li>creep speed in both directions of rotation</li> <li>pump ramp down</li> <li>DC braking</li> <li>motor heating</li> <li>slave pointer function</li> <li>trace function</li> </ul>	Yes Yes Yes Yes Yes Yes Yes Yes
<ul> <li>ramp-down (soft stop)</li> <li>breakaway pulse</li> <li>adjustable current limitation</li> <li>creep speed in both directions of rotation</li> <li>pump ramp down</li> <li>DC braking</li> <li>motor heating</li> <li>slave pointer function</li> <li>trace function</li> <li>intrinsic device protection</li> </ul>	Yes Yes Yes Yes Yes Yes Yes Yes
<ul> <li>ramp-down (soft stop)</li> <li>breakaway pulse</li> <li>adjustable current limitation</li> <li>creep speed in both directions of rotation</li> <li>pump ramp down</li> <li>DC braking</li> <li>motor heating</li> <li>slave pointer function</li> <li>trace function</li> </ul>	Yes Yes Yes Yes Yes Yes Yes Yes
<ul> <li>ramp-down (soft stop)</li> <li>breakaway pulse</li> <li>adjustable current limitation</li> <li>creep speed in both directions of rotation</li> <li>pump ramp down</li> <li>DC braking</li> <li>motor heating</li> <li>slave pointer function</li> <li>trace function</li> <li>intrinsic device protection</li> </ul>	Yes Yes Yes Yes Yes Yes Yes Yes Yes Yes
<ul> <li>ramp-down (soft stop)</li> <li>breakaway pulse</li> <li>adjustable current limitation</li> <li>creep speed in both directions of rotation</li> <li>pump ramp down</li> <li>DC braking</li> <li>motor heating</li> <li>slave pointer function</li> <li>trace function</li> <li>intrinsic device protection</li> <li>motor overload protection</li> </ul>	Yes Yes Yes Yes Yes Yes Yes Yes Yes Yes
<ul> <li>ramp-down (soft stop)</li> <li>breakaway pulse</li> <li>adjustable current limitation</li> <li>creep speed in both directions of rotation</li> <li>pump ramp down</li> <li>DC braking</li> <li>motor heating</li> <li>slave pointer function</li> <li>trace function</li> <li>intrinsic device protection</li> <li>motor overload protection</li> <li>evaluation of thermistor motor protection</li> </ul>	Yes Yes Yes Yes Yes Yes Yes Yes Yes Yes
<ul> <li>ramp-down (soft stop)</li> <li>breakaway pulse</li> <li>adjustable current limitation</li> <li>creep speed in both directions of rotation</li> <li>pump ramp down</li> <li>DC braking</li> <li>motor heating</li> <li>slave pointer function</li> <li>trace function</li> <li>intrinsic device protection</li> <li>motor overload protection</li> <li>evaluation of thermistor motor protection</li> <li>inside-delta circuit</li> </ul>	Yes Yes Yes Yes Yes Yes Yes Yes Yes Yes
<ul> <li>ramp-down (soft stop)</li> <li>breakaway pulse</li> <li>adjustable current limitation</li> <li>creep speed in both directions of rotation</li> <li>pump ramp down</li> <li>DC braking</li> <li>motor heating</li> <li>slave pointer function</li> <li>trace function</li> <li>trace function</li> <li>intrinsic device protection</li> <li>motor overload protection</li> <li>evaluation of thermistor motor protection</li> <li>inside-delta circuit</li> <li>auto-RESET</li> </ul>	Yes Yes Yes Yes Yes Yes Yes Yes Yes Yes
<ul> <li>ramp-down (soft stop)</li> <li>breakaway pulse</li> <li>adjustable current limitation</li> <li>creep speed in both directions of rotation</li> <li>pump ramp down</li> <li>DC braking</li> <li>motor heating</li> <li>slave pointer function</li> <li>trace function</li> <li>intrinsic device protection</li> <li>motor overload protection</li> <li>evaluation of thermistor motor protection</li> <li>inside-delta circuit</li> <li>auto-RESET</li> <li>manual RESET</li> </ul>	Yes Yes Yes Yes Yes Yes Yes Yes Yes Yes
<ul> <li>ramp-down (soft stop)</li> <li>breakaway pulse</li> <li>adjustable current limitation</li> <li>creep speed in both directions of rotation</li> <li>pump ramp down</li> <li>DC braking</li> <li>motor heating</li> <li>slave pointer function</li> <li>trace function</li> <li>intrinsic device protection</li> <li>motor overload protection</li> <li>evaluation of thermistor motor protection</li> <li>inside-delta circuit</li> <li>auto-RESET</li> <li>manual RESET</li> <li>remote reset</li> </ul>	Yes Yes Yes Yes Yes Yes Yes Yes Yes Yes
<ul> <li>ramp-down (soft stop)</li> <li>breakaway pulse</li> <li>adjustable current limitation</li> <li>creep speed in both directions of rotation</li> <li>pump ramp down</li> <li>DC braking</li> <li>motor heating</li> <li>slave pointer function</li> <li>trace function</li> <li>trace function</li> <li>intrinsic device protection</li> <li>motor overload protection</li> <li>inside-delta circuit</li> <li>auto-RESET</li> <li>manual RESET</li> <li>remote reset</li> <li>communication function</li> </ul>	Yes Yes Yes Yes Yes Yes Yes Yes Yes Yes
<ul> <li>ramp-down (soft stop)</li> <li>breakaway pulse</li> <li>adjustable current limitation</li> <li>creep speed in both directions of rotation</li> <li>pump ramp down</li> <li>DC braking</li> <li>motor heating</li> <li>slave pointer function</li> <li>trace function</li> <li>trace function</li> <li>intrinsic device protection</li> <li>motor overload protection</li> <li>inside-delta circuit</li> <li>auto-RESET</li> <li>manual RESET</li> <li>remote reset</li> <li>communication function</li> <li>operating measured value display</li> </ul>	Yes Yes Yes Yes Yes Yes Yes Yes Yes Yes
<ul> <li>ramp-down (soft stop)</li> <li>breakaway pulse</li> <li>adjustable current limitation</li> <li>creep speed in both directions of rotation</li> <li>pump ramp down</li> <li>DC braking</li> <li>motor heating</li> <li>slave pointer function</li> <li>trace function</li> <li>trace function</li> <li>intrinsic device protection</li> <li>motor overload protection</li> <li>evaluation of thermistor motor protection</li> <li>inside-delta circuit</li> <li>auto-RESET</li> <li>manual RESET</li> <li>remote reset</li> <li>communication function</li> <li>operating measured value display</li> <li>event list</li> </ul>	Yes Yes Yes Yes Yes Yes Yes Yes Yes Yes
<ul> <li>ramp-down (soft stop)</li> <li>breakaway pulse</li> <li>adjustable current limitation</li> <li>creep speed in both directions of rotation</li> <li>pump ramp down</li> <li>DC braking</li> <li>motor heating</li> <li>slave pointer function</li> <li>trace function</li> <li>intrinsic device protection</li> <li>motor overload protection</li> <li>inside-delta circuit</li> <li>auto-RESET</li> <li>remote reset</li> <li>communication function</li> <li>operating measured value display</li> <li>event list</li> <li>error logbook</li> </ul>	Yes Yes Yes Yes Yes Yes Yes Yes Yes Yes
<ul> <li>ramp-down (soft stop)</li> <li>breakaway pulse</li> <li>adjustable current limitation</li> <li>creep speed in both directions of rotation</li> <li>pump ramp down</li> <li>DC braking</li> <li>motor heating</li> <li>slave pointer function</li> <li>trace function</li> <li>intrinsic device protection</li> <li>motor overload protection</li> <li>inside-delta circuit</li> <li>auto-RESET</li> <li>remote reset</li> <li>communication function</li> <li>operating measured value display</li> <li>event list</li> <li>error logbook</li> <li>via software parameterizable</li> </ul>	Yes Yes Yes Yes Yes Yes Yes Yes Yes Yes
<ul> <li>ramp-down (soft stop)</li> <li>breakaway pulse</li> <li>adjustable current limitation</li> <li>creep speed in both directions of rotation</li> <li>pump ramp down</li> <li>DC braking</li> <li>motor heating</li> <li>slave pointer function</li> <li>trace function</li> <li>trace function</li> <li>intrinsic device protection</li> <li>motor overload protection</li> <li>inside-delta circuit</li> <li>auto-RESET</li> <li>remote reset</li> <li>communication function</li> <li>operating measured value display</li> <li>event list</li> <li>error logbook</li> <li>via software parameterizable</li> <li>via software configurable</li> </ul>	Yes Yes Yes Yes Yes Yes Yes Yes Yes Yes
<ul> <li>ramp-down (soft stop)</li> <li>breakaway pulse</li> <li>adjustable current limitation</li> <li>creep speed in both directions of rotation</li> <li>pump ramp down</li> <li>DC braking</li> <li>motor heating</li> <li>slave pointer function</li> <li>trace function</li> <li>trace function</li> <li>intrinsic device protection</li> <li>motor overload protection</li> <li>inside-delta circuit</li> <li>auto-RESET</li> <li>remote reset</li> <li>communication function</li> <li>operating measured value display</li> <li>event list</li> <li>error logbook</li> <li>via software parameterizable</li> <li>via software configurable</li> <li>screw terminal</li> </ul>	Yes Yes Yes Yes Yes Yes Yes Yes Yes Yes

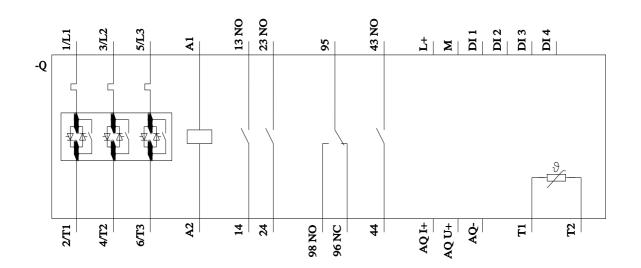
<ul> <li>removable terminal for control circuit</li> </ul>	Yes				
	Yes				
<ul> <li>voltage ramp</li> <li>torque control</li> </ul>	Yes				
combined braking	Yes				
analog output	Yes; 4 20 mA (default) / 0 10 V				
<ul> <li>programmable control inputs/outputs</li> </ul>	Yes				
condition monitoring	Yes				
automatic parameterisation					
-	Yes				
<ul> <li>application wizards</li> <li>alternative run-down</li> </ul>	Yes				
	Yes				
emergency operation mode	Yes				
reversing operation					
soft starting at heavy starting conditions	Yes				
Power Electronics operational current					
at 40 °C rated value	210 A				
at 40 °C rated value minimum	42 A				
at 50 °C rated value	42 A 186 A				
at 50 °C rated value     at 60 °C rated value	100 A				
<ul> <li>operational current at inside-delta circuit</li> <li>at 40 °C rated value</li> </ul>	364 A				
at 40 °C rated value     at 50 °C rated value	304 A 322 A				
at 50 °C rated value     at 60 °C rated value	322 A 294 A				
	294 A				
operating voltage	200 400 \/				
rated value	200 480 V				
at inside-delta circuit rated value	200 480 V -15 %				
relative negative tolerance of the operating voltage	-15 %				
relative positive tolerance of the operating voltage	-15 %				
relative negative tolerance of the operating voltage at inside-delta circuit	-15 %				
relative positive tolerance of the operating voltage at inside-delta circuit	10 %				
operating power for 3-phase motors					
<ul> <li>at 230 V at 40 °C rated value</li> </ul>	55 kW				
<ul> <li>at 230 V at inside-delta circuit at 40 °C rated value</li> </ul>	110 kW				
• at 400 V at 40 °C rated value	110 kW				
<ul> <li>at 400 V at inside-delta circuit at 40 °C rated value</li> </ul>	200 kW				
Operating frequency 1 rated value	50 Hz				
Operating frequency 2 rated value	60 Hz				
relative negative tolerance of the operating frequency	-10 %				
relative positive tolerance of the operating frequency	10 %				
minimum load [%]	10 %; Relative to set le				
power loss [W] for rated value of the current at AC					
● at 40 °C after startup	63 W				
● at 50 °C after startup	56 W				
● at 60 °C after startup	51 W				
power loss [W] at AC at current limitation 350 %					
● at 40 °C during startup	3 550 W				
● at 50 °C during startup	2 967 W				
● at 60 °C during startup	2 605 W				
type of the motor protection	Electronic, tripping in the event of thermal overload of the motor				
Control circuit/ Control					
type of voltage of the control supply voltage	AC				
control supply voltage at AC					
• at 50 Hz	110 250 V				
• at 60 Hz	110 250 V				
relative negative tolerance of the control supply voltage at AC at 50 Hz	-15 %				
relative positive tolerance of the control supply voltage at AC at 50 Hz	10 %				
relative negative tolerance of the control supply voltage at AC at 60 Hz	-15 %				

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relative positive tolerance of the control supply voltage at AC at 60 Hz	10 %				
control supply voltage frequency	50 60 Hz				
relative negative tolerance of the control supply voltage frequency	-10 %				
relative positive tolerance of the control supply voltage frequency	10 %				
control supply current in standby mode rated value	100 mA				
holding current in bypass operation rated value	150 mA				
inrush current by closing the bypass contacts maximum	0.87 A				
inrush current peak at application of control supply voltage maximum	43 A				
duration of inrush current peak at application of control supply voltage	1.6 ms				
design of the overvoltage protection	Varistor				
design of short-circuit protection for control circuit	4 A gG fuse (Icu=1 kA), 6 A quick-acting fuse (Icu=1 kA), C1 miniature circuit breaker (Icu= 600 A), C6 miniature circuit breaker (Icu= 300 A); Is not part of scope of supply				
Inputs/ Outputs					
number of digital inputs	4				
parameterizable	4				
<ul> <li>number of digital outputs</li> </ul>	4				
<ul> <li>number of digital outputs parameterizable</li> </ul>	3				
<ul> <li>number of digital outputs not parameterizable</li> </ul>	1				
digital output version	3 normally-open contacts (NO) / 1 changeover contact (CO)				
number of analog outputs	1				
switching capacity current of the relay outputs					
<ul> <li>at AC-15 at 250 V rated value</li> </ul>	3 A				
<ul> <li>at DC-13 at 24 V rated value</li> </ul>	1 A				
Installation/ mounting/ dimensions					
mounting position	Vertical (can be rotated +/- 90° and tilted forward or backward +/- 22.5°)				
fastening method	screw fixing				
height	393 mm				
width	210 mm				
depth	203 mm				
required spacing with side-by-side mounting					
• forwards	10 mm				
backwards	0 mm				
• upwards	100 mm				
downwards	75 mm				
• at the side	5 mm				
weight without packaging	10.2 kg				
Connections/ Terminals					
type of electrical connection					
for main current circuit	busbar connection				
for control circuit	screw-type terminals				
width of connection bar maximum	45 mm				
wire length for thermistor connection					
<ul> <li>with conductor cross-section = 0.5 mm<sup>2</sup> maximum</li> </ul>	50 m				
<ul> <li>with conductor cross-section = 1.5 mm<sup>2</sup> maximum</li> </ul>	150 m				
• with conductor cross spation = $2.5 \text{ mm}^2$ maximum					
<ul> <li>with conductor cross-section = 2.5 mm<sup>2</sup> maximum</li> </ul>	250 m				
• With conductor cross-section = 2.5 mm <sup>2</sup> maximum type of connectable conductor cross-sections	250 m				
	250 m 2x (50 240 mm²)				
type of connectable conductor cross-sections					
type of connectable conductor cross-sections • for DIN cable lug for main contacts stranded	2x (50 240 mm²)				
<ul> <li>type of connectable conductor cross-sections</li> <li>for DIN cable lug for main contacts stranded</li> <li>for DIN cable lug for main contacts finely stranded</li> </ul>	2x (50 240 mm²)				
<ul> <li>type of connectable conductor cross-sections</li> <li>for DIN cable lug for main contacts stranded</li> <li>for DIN cable lug for main contacts finely stranded</li> <li>type of connectable conductor cross-sections</li> </ul>	2x (50 240 mm²) 2x (70 240 mm²) 1x (0.5 4.0 mm²), 2x (0.5 2.5 mm²)				
type of connectable conductor cross-sections <ul> <li>for DIN cable lug for main contacts stranded</li> <li>for DIN cable lug for main contacts finely stranded</li> </ul> <li>type of connectable conductor cross-sections <ul> <li>for control circuit solid</li> </ul> </li>	2x (50 240 mm <sup>2</sup> ) 2x (70 240 mm <sup>2</sup> ) 1x (0.5 4.0 mm <sup>2</sup> ), 2x (0.5 2.5 mm <sup>2</sup> ) 1x (0.5 2.5 mm <sup>2</sup> ), 2x (0.5 1.5 mm <sup>2</sup> )				
<ul> <li>type of connectable conductor cross-sections <ul> <li>for DIN cable lug for main contacts stranded</li> <li>for DIN cable lug for main contacts finely stranded</li> </ul> </li> <li>type of connectable conductor cross-sections <ul> <li>for control circuit solid</li> <li>for control circuit finely stranded with core end processing</li> <li>for AWG cables for control circuit solid</li> </ul> </li> </ul>	2x (50 240 mm²) 2x (70 240 mm²) 1x (0.5 4.0 mm²), 2x (0.5 2.5 mm²)				
type of connectable conductor cross-sections <ul> <li>for DIN cable lug for main contacts stranded</li> <li>for DIN cable lug for main contacts finely stranded</li> </ul> <li>type of connectable conductor cross-sections <ul> <li>for control circuit solid</li> <li>for control circuit finely stranded with core end processing</li> <li>for AWG cables for control circuit solid</li> </ul> </li> <li>wire length</li>	2x (50 240 mm <sup>2</sup> ) 2x (70 240 mm <sup>2</sup> ) 1x (0.5 4.0 mm <sup>2</sup> ), 2x (0.5 2.5 mm <sup>2</sup> ) 1x (0.5 2.5 mm <sup>2</sup> ), 2x (0.5 1.5 mm <sup>2</sup> ) 1x (20 12), 2x (20 14)				
<ul> <li>type of connectable conductor cross-sections <ul> <li>for DIN cable lug for main contacts stranded</li> <li>for DIN cable lug for main contacts finely stranded</li> </ul> </li> <li>type of connectable conductor cross-sections <ul> <li>for control circuit solid</li> <li>for control circuit finely stranded with core end processing</li> <li>for AWG cables for control circuit solid</li> </ul> </li> <li>wire length <ul> <li>between soft starter and motor maximum</li> </ul> </li> </ul>	2x (50 240 mm <sup>2</sup> ) 2x (70 240 mm <sup>2</sup> ) 1x (0.5 4.0 mm <sup>2</sup> ), 2x (0.5 2.5 mm <sup>2</sup> ) 1x (0.5 2.5 mm <sup>2</sup> ), 2x (0.5 1.5 mm <sup>2</sup> ) 1x (20 12), 2x (20 14) 800 m				
type of connectable conductor cross-sections <ul> <li>for DIN cable lug for main contacts stranded</li> <li>for DIN cable lug for main contacts finely stranded</li> </ul> <li>type of connectable conductor cross-sections <ul> <li>for control circuit solid</li> <li>for control circuit finely stranded with core end processing</li> <li>for AWG cables for control circuit solid</li> </ul> </li> <li>wire length</li>	2x (50 240 mm <sup>2</sup> ) 2x (70 240 mm <sup>2</sup> ) 1x (0.5 4.0 mm <sup>2</sup> ), 2x (0.5 2.5 mm <sup>2</sup> ) 1x (0.5 2.5 mm <sup>2</sup> ), 2x (0.5 1.5 mm <sup>2</sup> ) 1x (20 12), 2x (20 14)				

<ul> <li>for main contacts with screw-type terminals</li> </ul>	14 24 N·m		
<ul> <li>for auxiliary and control contacts with screw-type terminals</li> </ul>	0.8 1.2 N·m		
tightening torque [lbf·in]			
<ul> <li>for main contacts with screw-type terminals</li> </ul>	124 210 lbf·in		
<ul> <li>for auxiliary and control contacts with screw-type terminals</li> </ul>	7 10.3 lbf-in		
Ambient conditions			
installation altitude at height above sea level maximum	5 000 m; Derating as of 1000 m, see catalog		
ambient temperature	5 000 m, Derating as or 1000 m, see catalog		
during operation	-25 +60 °C; Please observe derating at temperatures of 40 °C or above		
during storage and transport	-40 +80 °C		
environmental category	-40 +00 C		
	2K6 (no ico formation, only accessional condensation), 2C2 (no calt mict), 2S2		
<ul> <li>during operation according to IEC 60721</li> </ul>	3K6 (no ice formation, only occasional condensation), 3C3 (no salt mist), 3S2 (sand must not get into the devices), 3M6		
• during storage according to IEC 60721	1K6 (only occasional condensation), 1C2 (no salt mist), 1S2 (sand must not get inside the devices), 1M4		
<ul> <li>during transport according to IEC 60721</li> </ul>	2K2, 2C1, 2S1, 2M2 (max. fall height 0.3 m)		
Environmental footprint			
Siemens Eco Profile (SEP)	Siemens EcoTech		
EMC emitted interference	acc. to IEC 60947-4-2: Class A		
Communication/ Protocol			
communication module is supported			
PROFINET standard	Yes		
PROFINET high-feature	Yes		
• EtherNet/IP	Yes		
Modbus RTU	Yes		
Modbus TCP	Yes		
PROFIBUS	Yes		
UL/CSA ratings			
manufacturer's article number			
of circuit breaker usable for Standard Faults			
- at 460/480 V according to UL	Siemens type: 3VA53, max. 400 A or 3VA54, max. 600 A; Ig = 10 kA		
- 60/480 V according to UL	Siemens type: 3VA53, max. 400 A or 3VA54, max. 600 A; Iq max = 65 kA		
— at 460/480 V at inside-delta circuit according to UL	Siemens type: 3VA53, max. 400 A or 3VA54, max. 600 A; Iq = 10 kA		
— 60/480 V at inside-delta circuit according to UL	Siemens type: 3VA53, max. 400 A or 3VA54, max. 600 A; Iq max = 65 kA		
— at 575/600 V according to UL	Siemens type: 3VA53, max. 400 A or 3VA54, max. 600 A; Iq = 10 kA		
C C			
<ul> <li>— 75/600 V at inside-delta circuit according to UL</li> <li>— at 575/600 V at inside-delta circuit according to UL</li> </ul>	Siemens type: 3VA53, max. 400 A or 3VA54, max. 600 A; Iq max = 65 kA		
of the fuse	Siemens type: 3VA53, max. 400 A or 3VA54, max. 600 A; Iq = 10 kA		
<ul> <li>or the fuse</li> <li>— usable for Standard Faults up to 575/600 V according to UL</li> </ul>	Type: Class J / L, max. 700 A; Iq = 10 kA		
— usable for High Faults up to 575/600 V according to UL	Type: Class J / L, max. 700 A; Iq = 100 kA		
<ul> <li>— usable for Standard Faults at inside-delta circuit up to 575/600 V according to UL</li> </ul>	Type: Class J / L, max. 700 A; Iq = 10 kA		
<ul> <li>— usable for High Faults at inside-delta circuit up to 575/600 V according to UL</li> </ul>	Type: Class J / L, max. 700 A; Iq = 100 kA		
operating power [hp] for 3-phase motors			
• at 200/208 V at 50 °C rated value	60 hp		
• at 220/230 V at 50 °C rated value	60 hp		
• at 460/480 V at 50 °C rated value	150 hp		
• at 200/208 V at inside-delta circuit at 50 °C rated value	100 hp		
• at 220/230 V at inside-delta circuit at 50 °C rated value	125 hp		
• at 460/480 V at inside-delta circuit at 50 °C rated value	250 hp		
contact rating of auxiliary contacts according to UL	R300-B300		
Electrical Safety			
protection class IP on the front according to IEC 60529	IP00; IP20 with cover		
touch protection on the front according to IEC 60529	finger-safe, for vertical contact from the front with cover		
ATEX			
Safety Integrity Level (SIL) according to IEC 61508 relating			
to ATEX	SIL1		

relating to ATEX						
PFDavg with low dema relating to ATEX	nd rate according to IE	C 61508	0.008	3		
hardware fault tolerance according to IEC 61508 relating to ATEX		0				
T1 value for proof test IEC 61508 relating to A		according to	3 a			
certificate of suitability	,					
• ATEX			Yes			
• IECEx			Yes			
<ul> <li>according to ATEX</li> </ul>	K directive 2014/34/EU		BVS	18 ATEX F 003 X		
type of protection acco	ording to ATEX directiv	e 2014/34/EU	II (2)G [Ex eb Gb] [Ex db Gb] [Ex pxb Gb], II (2)D [Ex tb Db] [Ex pxb Db], I (M2) [Ex db Mb]			
pprovals Certificates				~		
General Product Appro	oval					
	UK CA	Confirmation	ב	CE EG-Konf.		
General Product Approval	EMV			For use in hazardous	locations	Test Certificates
EHC	RCM	KC		IECEx	KEx ATEX	Type Test Certific- ates/Test Report
Marine / Shipping					other	Environment
ABS	BUREAU VERITAS	Llovd's Register urs		PRS	<u>Confirmation</u>	EPD
Environment						
Siemens EcoTech	Environmental Con- firmations					
urther information						
Information on the pac	kaqinq					
https://support.industry.s	iemens.com/cs/ww/en/v					
Information- and Down	loadcenter (Catalogs,	Brochures,)				
https://www.siemens.com						
Industry Mall (Online o https://mall.industry.siem	ruering system) hens.com/mall/en/en/Cat	alog/product?mlfh=	-3RW5	543-6HA14		
Cax online generator						
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https://support.industry.s	iemens.com/cs/ww/en/p	s/3RW5543-6HA14	1	, device circuit diagram	s, EPLAN macros,)	
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Simulation Tool for So https://support.industry.s	ft Starters (STS)				ALL REAL REAL REAL REAL REAL REAL REAL R	<u></u>





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